

# The dynamics of some cubic vector fields with a center

VESNA ŽUPANOVIĆ\*

**Abstract.** *We study planar cubic vector fields*

$$V_H = yP_2 \frac{\partial}{\partial x} - xQ_2 \frac{\partial}{\partial y}$$

*with a center, having Darboux first integral  $H = P_1^2 Q_3$ . We give the bifurcation diagram of the phase portraits of the vector fields, in 2-dimensional parameter space.*

**Key words:** *cubic vector fields*

**AMS subject classifications:** 58F14, 58F30

Received October 27, 2000

Accepted February 22, 2000

## 1. Introduction

In [P1], H. Poincaré defined a center of a real vector field on the plane as isolated singularity surrounded by closed integral curves. He showed in [P2] that a necessary and sufficient conditions for a polynomial vector field with a singular point with pure imaginary eigenvalues, to have a center at this point is the annihilation of an infinite number of polynomials in the coefficients of the vector field. The problem of explicitly finding a finite basis for these algebraic conditions, called the center problem, was solved in the case of quadratic vector fields by contributions of H. Dulac, W. Kapteyn and others.

It is well known that each quadratic vector field with a center also possesses an explicit first integral (constant of motion) defined and analytic at least in an open domain around the center. This is the reason why such systems are called integrable.

For polynomial vector fields of degree  $n \geq 3$  the center problem is not solved. In [M] Malkin found necessary and sufficient conditions for cubic vector field with no quadratic terms, to have a center. In [LS] Lunkevich and Sibirsky proved that the integrability of the systems satisfying these conditions.

In [S] Schlomiuk gives a background for work on the center problem for general cubic vector field. Algebraic particular integrals are used in exploring conditions

---

\*Department of Applied Mathematics, Faculty of Electrical Engineering and Computing, Unska 3, HR-10 000 Zagreb, Croatia, e-mail: vesna@zpm.fer.hr

1 for the center; because the problem of calculating a finite basis for these conditions,  
 2 using the computer, were leading to enormous expressions.

3 The center problem plays an important role in the Hilbert's 16th problem which  
 4 asks for the maximum number of limit cycles of a polynomial vector field of degree  
 5  $n$ . One way to produce limit cycles is by perturbing a vector field which has a  
 6 continous family of closed orbits. In order to do it we have to describe the global  
 7 geometry of the some class of vector fields and then make the perturbation.

8 In recent years progress has been made concerning singularities which are centers.  
 9 This progress was due partly to studies of specific classes of vector fields, partly  
 10 to theoretical development. In [RS], a detailed study of the cubic vector fields sym-  
 11 metric with respect to a center is done. In [MM-JR], a new two-parameter family  
 12 of cubic isochronous centers is found. In [RST], the centers in the reduced Kukles  
 13 systems are studied, and in [T] the perturbation of isochronous centers of Kukles  
 14 systems are studied. The authors of [RST] said that more work concerning specific  
 15 classes of systems needs to be done. This article is a part of this effort; we want  
 16 to describe the geometry of a specific class of vector fields with a center. Our next  
 17 step, in future, will be the study of perturbed vector fields created from this class  
 18 of vector fields.

19 When we place a center at the origin, a cubic vector field can be written in the  
 20 form

$$\begin{aligned} \dot{x} &= -y + \sum_{i+j=2}^3 a_{ij}x^i y^j \\ \dot{y} &= x + \sum_{i+j=2}^3 b_{ij}x^i y^j, \quad a_{ij}, b_{ij} \in \mathbb{R}. \end{aligned} \tag{1}$$

24 We study such cubic vector fields denoted by  $V_H = P(x, y)\frac{\partial}{\partial x} + Q(x, y)\frac{\partial}{\partial y}$ , under  
 25 two conditions:

26 a) the first Darboux integral of  $V_H = P(x, y)\frac{\partial}{\partial x} + Q(x, y)\frac{\partial}{\partial y}$  is

$$H(x, y) = P_1(x, y)^2 Q_3(x, y),$$

28 where  $P_1, Q_3$  are polynomials of degree 1, respectively 3;

29 b)

$$\begin{aligned} P(x, y) &= yP_2(x, y) \\ Q(x, y) &= -xQ_2(x, y) \end{aligned}$$

31 where  $P_2, Q_2$  are polynomials of degree 2.

32 We need to explain why these conditions are taken.

33 The condition a) gives us a vector field which is not Hamiltonian. The Hamil-  
 34 tonian vector fields are studied quite often, see [PS] where quadratic Hamiltonian  
 35 vector fields with a center are studied. We wanted to study cubic Hamiltonian  
 36 vector fields under some conditions; and noticed that if we take a first integral  
 37  $H_1 = P_1 Q_3$ , there is only one 3-parameter vector field satisfying condition b) and

1 it has the bifurcation diagram induced by the bifurcation diagram of vector field  
 2 with a first integral  $H = P_1^2 Q_3$ . More about this statement will be said at the end  
 3 of the article, in *Remark 5*.

4 Moreover, Hamiltonian vector field  $X_H$  with Hamiltonian  $H = P_1^2 Q_3$  satisfies  
 5  $X_H = P_1 W_H$  where  $W_H$  is a vector field with a first integral  $H = P_1^2 Q_3$ . We obtain  
 6  $V_H$  from  $W_H$  satisfying condition b).

7 The condition b) is taken because of easier computation with less parameters.  
 8 Without the condition b) we would compute with 7 parameters of the system (13 to  
 9 describe the two invariant curves, minus 6 to delete the action of the affine group).

10 Then, we give the bifurcation diagram of the phase portraits of the vector fields  
 11  $V_H$  under the conditions a) and b).

## 12 2. Basic notions

13 First we briefly recall the main notions of invariant algebraic curves. Given a  
 14 polynomial system

$$\begin{aligned} 15 \quad \dot{x} &= P(x, y) \\ 16 \quad \dot{y} &= Q(x, y) \end{aligned} \tag{2}$$

18 of degree  $n$ , define the differential operator

$$19 \quad DF = \dot{F} = F_x P + F_y Q. \tag{3}$$

### 20 Definition 1.

21 (1) An invariant algebraic curve of the system (2) is a curve in the complex plane  
 22 given by the equation  $F(x, y) = 0$  with  $F(x, y) \in \mathbb{C}[x, y]$ , such that there exists  
 23  $K(x, y) \in \mathbb{C}[x, y]$  satisfying

$$24 \quad DF(x, y) = F(x, y)K(x, y) \tag{4}$$

25 where  $K(x, y) \in \mathbb{C}_{n-1}[x, y]$ .

26 (2) A Darboux factor is a polynomial  $F(x, y)$  such that  $F(x, y) = 0$  is an invariant  
 27 curve.

28 (3) Any analytic function satisfying (4) for some  $K(x, y) \in \mathbb{C}_{n-1}[x, y]$ , is an an-  
 29 alytic Darboux factor. The polynomial  $K(F) = K(x, y)$  is called the cofactor  
 30 of the analytic Darboux factor.

31 (4) A non-constant function  $F(x, y)$  satisfying  $DF(x, y) \equiv 0$  is a first integral.

32 **Definition 2.** A Darboux function is a function  $Z(x, y)$  of the form

$$33 \quad \prod_{j=0}^k F_j^{\alpha_j}, \quad \alpha_j \in \mathbb{C}$$

34 with  $F_j \in \mathbb{C}[z, \bar{z}] = \mathbb{C}[x, y]$ , for each  $j = 0, \dots, k$ .

35 An important class of strata of centers of polynomial systems in the class of  
 36 strata of Darboux integrable systems i.e. systems which have a Darboux function  
 37 as a first integral. For more details see [MM-JR], [S] and [So].

### 1 3. Systems satisfying conditions a) and b)

2 In the paper of Sokulski [So], the Darboux integral  $H = P_1^\alpha Q_3^\beta$  is given, where  $P_1$   
3 and  $Q_3$  are the invariant curves of the vector field  $V_H$ . The vector field

$$4 \quad V_H = \alpha Q_3 \left( \frac{\partial P_1}{\partial y} \frac{\partial}{\partial x} - \frac{\partial P_1}{\partial x} \frac{\partial}{\partial y} \right) + \beta P_1 \left( \frac{\partial Q_3}{\partial y} \frac{\partial}{\partial x} - \frac{\partial Q_3}{\partial x} \frac{\partial}{\partial y} \right)$$

5 has a center at the origin if linear part of  $V_H$  is  $y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y}$ .

6 Let  $P_1(x, y) = ax + by + c$ ,  $Q_3(x, y) = dx^3 + ex^2y + fxy^2 + gy^3 + hx^2 + jxy +$   
7  $ky^2 + lx + my + n$  and  $ck \neq 0$ . We take  $\alpha = 2$ ,  $\beta = 1$ , and divide  $H = P_1^2 Q_3$  by  
8  $c^2 k$ . We define new coefficients, they are the quotients obtained after that dividing;  
9 or just simply take  $c = k = 1$ . These new coefficients will be denoted by capital  
10 letters.

11 If  $V_H = P \frac{\partial}{\partial x} + Q \frac{\partial}{\partial y}$  satisfies the condition b), the first integrals in the form  
12  $P_1^2 Q_3$  are

$$13 \quad \begin{aligned} H_A(x, y) &= (Ax + 1)^2 (Dx^3 - 2Axy^2 + (1 - \frac{3}{2}AL)x^2 + y^2 + Lx - \frac{L}{2A}), \\ &A \neq 0, \quad A, D, L \in \mathbb{R}, \end{aligned}$$

14 and

$$15 \quad \begin{aligned} H(x, y) &= (Ax + By + 1)^2 \left( (A - 3A^2L + \frac{3}{2}B^2L)x^3 + B(-2 + 6AL - \frac{3B^2L}{A})x^2y \right. \\ &+ (-2A + 3B^2L)xy^2 - \frac{B}{2A}(-2A + 3B^2L)y^3 + (1 + \frac{3}{2}(\frac{B^2L}{A} - AL))x^2 \\ &\left. - 3BLxy + y^2 + Lx + \frac{BL}{A}y - \frac{L}{2A} \right), \quad A, B \neq 0, \quad A, B, L \in \mathbb{R}. \end{aligned}$$

16 If  $h \neq 0$ , then by taking  $c = h = 1$  we get the integral

$$17 \quad \begin{aligned} H_B(x, y) &= (By + 1)^2 (-2Bx^2y + Gy^3 + x^2 + (1 - \frac{3}{2}BL)y^2 + Ly - \frac{L}{2B}), \\ &B \neq 0, \quad B, G, L \in \mathbb{R}. \end{aligned}$$

18 We can see that  $H_B(x, y) = H_A(y, x)$  depending on three real parameters and  
19 it is not necessary to study both of them.

20 The system with the first integral  $H_A$  is

$$21 \quad \begin{aligned} \dot{x} &= y(2 - 2Ax - 4A^2x^2) \\ 22 \quad \dot{y} &= -x(2 + (4A + 3D - 6A^2L)x + 5ADx^2 - 6A^2y^2), \quad A \neq 0, \end{aligned} \quad (5)$$

24 the system with the first integral  $H_B$  is

$$25 \quad \begin{aligned} \dot{x} &= y(2 + (4B + 3G - 6B^2L)y + 5BGy^2 - 6B^2x^2) \\ 26 \quad \dot{y} &= -x(2 - 2By - 4B^2y^2), \quad B \neq 0, \end{aligned} \quad (6)$$

1 and the system with the first integral  $H$  is

$$\begin{aligned}
 2 \quad \dot{x} &= y(-4A - 6B^2L + 4A^2x + 6AB^2Lx + 8A^3x^2 + 12AB^2x^2 - 48A^2B^2Lx^2 \\
 3 &\quad + 18B^4Lx^2 - 14AB^2y + 9B^3Ly + 10A^2Bxy - 15AB^3Lxy \\
 4 &\quad - 10AB^2y^2 + 15B^4Ly^2) \\
 5 \quad \dot{y} &= -x(-4A - 6B^2L - 14A^2x + 30A^3Lx - 21AB^2Lx - 10A^3x^2 \quad (7) \\
 6 &\quad + 30A^4Lx^2 - 15A^2B^2Lx^2 + 4AB^2y + 6B^3Ly + 10A^2Bxy - 30A^3BLxy \\
 7 &\quad + 15AB^3Lxy + 12A^3y^2 + 8AB^2y^2 - 42A^2B^2Ly^2 + 12B^4Ly^2), \quad A, B \neq 0.
 \end{aligned}$$

9 In this paper we study systems (5) and (7) with  $L = 0$ . The complete study of  
 10 the systems (5) and (7) is quite long and we divided it into two natural parts, by  
 11 means of the number of parameters of the systems. This part for  $L = 0$  is simpler  
 12 than the part for  $L \neq 0$  described in [Ž1].

#### 13 4. Phase portraits of the systems (5) for $L = 0$ and their 14 bifurcation diagram

15 We begin by studying the nature of the singularities of the system

$$\begin{aligned}
 16 \quad \dot{x} &= yP_{2A}(x, y) = y(2 - 2Ax - 4A^2x^2) \\
 17 \quad \dot{y} &= -xQ_{2A}(x, y) = -x(2 + (4A + 3D)x + 5ADx^2 - 6A^2y^2). \quad (8)
 \end{aligned}$$

19 Notice that we can simplify (8) by changing the coordinates

$$\begin{aligned}
 20 \quad u &= Ax \\
 v &= Ay,
 \end{aligned}$$

21 and by substituting  $M = \frac{D}{A}$ , then we get

$$\begin{aligned}
 22 \quad \dot{u} &= v\bar{P}_{2A}(u, v) = v(2 - 2u - 4u^2) \\
 23 \quad \dot{v} &= -u\bar{Q}_{2A}(u, v) = -u(2 + (3M + 4)u + 5Mu^2 - 6v^2). \quad (9)
 \end{aligned}$$

25 We will study the system (9).

26 **Remark 1.** Notice that the function  $P_{2A}$  is symmetric under

$$\begin{aligned}
 27 \quad (x, y, A) &\mapsto (-x, y, -A), \\
 (x, y, A) &\mapsto (-x, -y, -A),
 \end{aligned}$$

28 and  $Q_{2A}$  is symmetric under

$$\begin{aligned}
 29 \quad (x, y, A, D) &\mapsto (-x, y, -A, -D), \\
 (x, y, A, D) &\mapsto (-x, -y, -A, -D).
 \end{aligned}$$

30 There is another symmetry, between  $Q_{2A}$  and  $P_{2B}$

$$31 \quad (x, y, A, D) \mapsto (y, x, B, G),$$

1 and between  $P_{2A}$  and  $Q_{2B}$ ; where  $P_{2B}$ ,  $Q_{2B}$  are polynomials obtained from  $H_B$  in  
 2 the same way as  $P_{2A}$ ,  $Q_{2A}$ .

3 **Remark 2.** From Definition 1 we can see that the cofactors of the system (8)  
 4 are:  $K_{1A}(x, y) = 2Ay(1 - 2Ax)$  is the cofactor of  $P_1(x, y) = 0$ ; and  $K_{2A}(x, y) =$   
 5  $-2K_{1A}(x, y)$  is the cofactor of  $Q_3(x, y) = 0$ .

6 **Proposition 1.** System (9) has the following singular points on the coordinate  
 7 axes:

8 (1) the origin which is a center;

9 (2)  $S_{1A}(M) = (\frac{-3M-4+\sqrt{9M^2-16M+16}}{10M}, 0)$ , for  $M \neq 0$ , which is a saddle;

10 (3)  $S_{3A}(M) = (\frac{-3M-4-\sqrt{9M^2-16M+16}}{10M}, 0)$ , for  $M \neq 0$ , which is a saddle for  
 11  $M \in (-\infty, -16/11] \cup (0, 1]$ , a center for  $M \in (-16/11, 0) \cup (1, \infty)$ ;

12 (4)  $S = (-1/2, 0)$  if  $M = D = 0$ , which is a saddle.

13 **Proof.**

14 (2) For studying the singularity  $S_{1A}$ , we first translate the singularity into the  
 15 origin; then we look for the eigenvalues, and see that the eigenvalues are real  
 16 functions of  $M$ . We find that  $\lambda_1(M) = -\lambda_2(M)$  and  $\lambda_1^2(M) = \lambda_2^2(M)$  is a  
 17 positive function of  $M$ .

18 (3) In the case when  $M = 1$  and  $M = -16/11$ , we see that we have the nilpo-  
 19 tent case i.e. the linear part is  $u\frac{\partial}{\partial v}$ . Then, we can simply see [D], or we can  
 20 find the principal part defined through the Newton diagram (see [BM], [Ž]).  
 21 The vector field  $V_{H_A t}$ , obtained by translation, is locally topologically equiv-  
 22 alent to its principal part. After a quasi-homogeneous blowing-up of type  
 23 of quasi-homogeneity  $(2, 1)$ , we have a decomposition of the singularity into  
 24 the elementary singularities, and, after blowing-down, we see that we have a  
 25 saddle.

26 **Proposition 2.**

27 (i) System (9) has the following singular points:

28 (1)  $T_{1A}(M) = (-1, \sqrt{M-1}/\sqrt{3})$ , for  $M \geq 1$ , which is a saddle with eigen-  
 29 values  $\lambda_1 = -4\sqrt{3}\sqrt{M-1}$  and  $\lambda_2 = 2\sqrt{3}\sqrt{M-1}$ ;

30 (2)  $T_{2A}(M) = (-1, -\sqrt{M-1}/\sqrt{3})$ , for  $M \geq 1$ , which is a saddle with eigen-  
 31 values  $\lambda_1 = 4\sqrt{3}\sqrt{M-1}$  and  $\lambda_2 = -2\sqrt{3}\sqrt{M-1}$ ;

32 (3)  $T_{3A}(M) = (1/2, \sqrt{16+11M}/(2\sqrt{6}))$ , for  $M \geq -16/11$ , which is a saddle  
 33 with eigenvalues  $\lambda_1 = \sqrt{\frac{3}{2}}\sqrt{16+11M}$  and  $\lambda_2 = -\sqrt{\frac{3}{2}}\sqrt{16+11M}$ ;

34 (4)  $T_{4A}(M) = (1/2, -\sqrt{16+11M}/(2\sqrt{6}))$ , for  $M \geq -16/11$ , which is a sad-  
 35 dle with eigenvalues  $\lambda_1 = -\sqrt{\frac{3}{2}}\sqrt{16+11M}$  and  $\lambda_2 = \sqrt{\frac{3}{2}}\sqrt{16+11M}$ ;

36 (ii) System (9) has singular points at infinity:

- 1 (1) three pairs if  $M > 0$ , then the singular points in  $P_2(\mathbb{R})$  are:  
 2 (a)  $(0 : 1 : 0)$  which is not elementary;  
 3 (b)  $(1 : \sqrt{M/2} : 0)$ , which is a node;  
 4 (c)  $(1 : -\sqrt{M/2} : 0)$  which is a node;  
 5 (2) two pairs if  $M = 0$ , then the singular points are:  
 6 (a)  $(0 : 1 : 0)$  which is not elementary;  
 7 (b)  $(1 : 0 : 0)$  which is not elementary;  
 8 (3) one pair if  $M < 0$ , then the singular point is:  
 9 (a)  $(0 : 1 : 0)$  which is not elementary.

10 **Proof.**

11 (i) Both singular points

12  $T_{1A}(1) = T_{2A}(1) = S_{3A}(1)$  and  $T_{3A}(-16/11) = T_{4A}(-16/11) = S_{3A}(-16/11)$

13 are saddles.

14 (ii) For the study of singular points at infinity we use the variables  $Z, U$  with the  
 15 change  $Z = 1/u, U = v/u$  corresponding to the needed two charts. We have  
 16 the vector field

17 
$$(-2UZ^3 + 2UZ^2 + 4UZ) \frac{\partial}{\partial Z} + (-2U^2Z^2 + 2U^2Z + 4U^2 - 2Z^2 - (3M+4)Z - 5M + 6U^2) \frac{\partial}{\partial U}$$

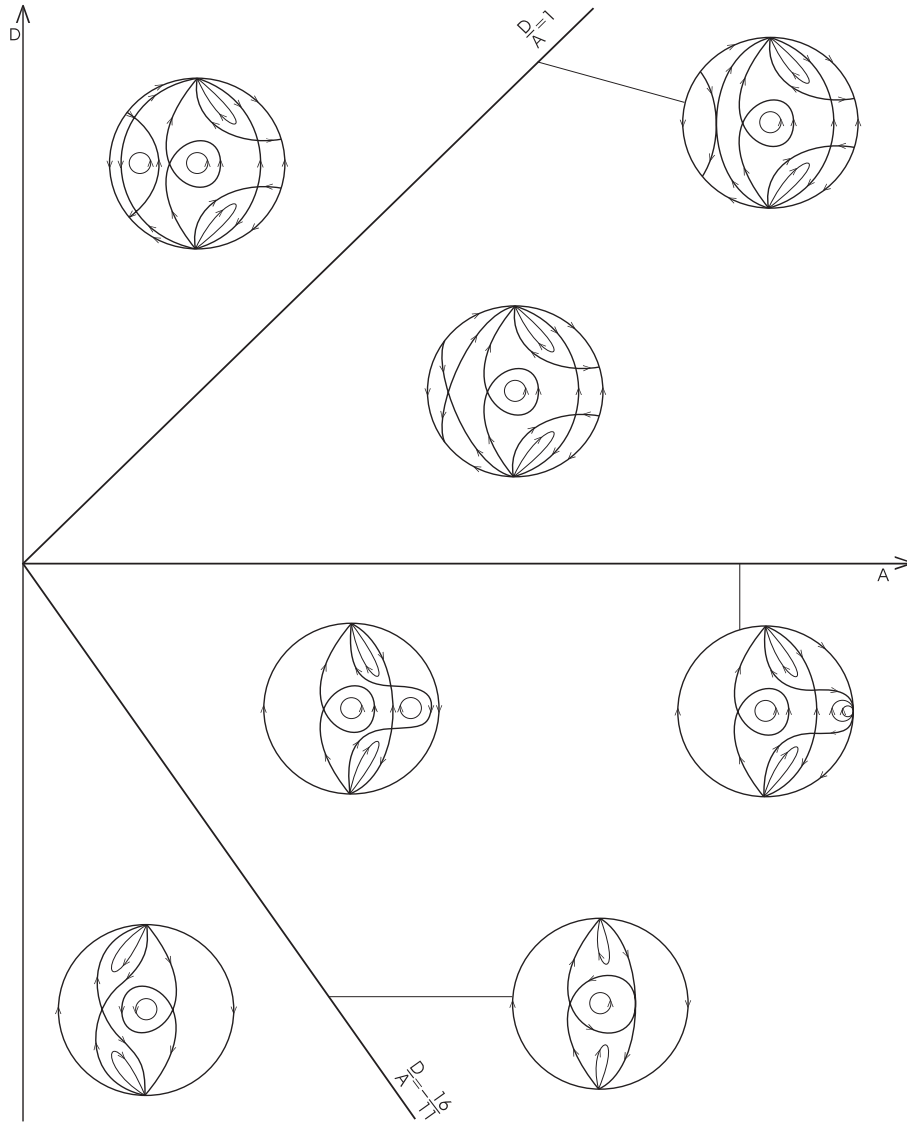
18 with singularities  $(Z = 0, U = \sqrt{M/2}), (Z = 0, U = -\sqrt{M/2})$  i.e.  
 19  $(1 : \sqrt{M/2} : 0), (1 : -\sqrt{M/2} : 0)$ . These singular points are nodes for  $M \neq 0$ .

20 In the another chart we see the singular point  $(0 : 1 : 0)$  which is nonele-  
 21 mentary; we check the topological type using the Newton diagram and the  
 22 blowing-up. Analogously for the singularity  $(1 : 0 : 0)$  in the case  $M = 0$ .

23 □  
 24 The system with the first integral  $H_B(x, y) = (By + 1)^2(x^2 + y^2 + Gy^3 - 2Bx^2y)$   
 25 can be checked in the same way as we have done it for  $H_A(x, y) = (Ax + 1)^2(x^2 +$   
 26  $y^2 + Dx^3 - 2Axy^2)$ .

27 The phase portraits of the system (8) are drawn on the Poincaré disc. Due to  
 28 the symmetry of the system (9), it is only necessary to draw the bifurcation diagram  
 29 for systems (8) on the semi-plane with  $A > 0$ . The bifurcation diagram appears at  
 30 *Figure 1*.

1



2

Figure 1.

### 3 5. Invariant curves of the systems (8)

4 The zero level invariant curves of (4.1.) are two algebraic curves, a straight line  
 5  $P_{1A}(x, y) = Ax + 1 = 0$ , and a cubic curve  $Q_{3A}(x, y) = Dx^3 - 2Axy^2 + x^2 + y^2 = 0$ ,  
 6 which are factors of  $H_A(x, y) = (Ax + 1)^2(Dx^3 - 2Axy^2 + x^2 + y^2) = 0$ .

1        The changes of the phase portraits are related to the changes of the invariant  
 2        curves. For a family of cubic curves depending on parameters, a point in the  
 3        parameter space will be called a bifurcation point if any neighborhood of this point  
 4        contains points with cubics of different affine types. We use the term bifurcation  
 5        to indicate any qualitative, topological modification obtained for the curves we  
 6        consider as a consequence of the variation of the parameters.

7        If  $A = 0$  then the straight line becomes the line at infinity; for  $D = 0$  the number  
 8        of the connected components of  $Q_{3A} = 0$  is changed, for  $D = 0$  is 2, for  $D < 0$  is 1,  
 9        and for  $D > 0$  is 3 (it is obvious from  $y^2 = \frac{x^2(Dx+1)}{2Ax-1}$ ); if  $A = D = 0$  then the cubic  
 10       curve becomes the reducible conic  $x^2 + y^2 = 0$ ; if  $D = -2A$  then the cubic curve  
 11       becomes the reducible curve  $(x^2 + y^2)(1 - 2Ax) = 0$ .

12       **Example 1.** *In this example we describe the invariant curves of the system (8)*  
 13       *for  $A = D$ . The singularity  $(-1/A, 0)$  lies on the curves  $P_{1A} = 0$  and  $Q_{3A} = 0$ , these*  
 14       *curves passes through this point. The origin lies on the curve  $Q_{3A} = 0$ , but the curve*  
 15       *does not pass through. The saddles  $(1/(2A), 3/(2\sqrt{2}A))$  and  $(1/(2A), -3/(2\sqrt{2}A))$*   
 16       *lie on the curve  $H_A = P_{1A}^2 Q_{3A} = C$ ,  $C \neq 0$  and we have a saddle connection.*  
 17       *The singularity  $(-2/(5A), 0)$  lies on the curve  $H_A = P_{1A}^2 Q_{3A} = C$ , for some other*  
 18        *$C \neq 0$ , this point is a self-intersecting point of the curve.*

19       *The phase portraits at Figure1 are determined by the bifurcations of the curves*  
 20        *$P_{1A} = 0$  and  $Q_{3A} = 0$ , and also by the bifurcations of the curve  $H_A = C$ ,  $C \neq 0$ .*

## 21        6. Phase portraits of the systems (7) for $L = 0$ and their 22        bifurcation diagram

23        We have to find singularities of the system

24         $\dot{x} = yP_2(x, y) = y(2 + 7By - 2Ax + 5B^2y^2 - 5ABxy - 2(2A^2 + 3B^2)x^2)$   
 25         $\dot{y} = -xQ_2(x, y) = -x(2 + 7Ax - 2By + 5A^2x^2 - 5ABxy - 2(3A^2 + 2B^2)y^2)$ .<sup>(10)</sup>  
 26

27        Notice that we can simplify (10) in the similar way as (8). We take change of the  
 28        coordinates

29        
$$\begin{aligned} u &= Ax \\ v &= By, \end{aligned}$$

30        and the substitution  $F = \frac{A^2}{B^2}$ , then we get

31         $\dot{u} = v\bar{P}_2(u, v) = v(2F + 7Fv - 2Fu + 5Fv^2 - 5Fuv - 2(2F + 3)u^2)$   
 32         $\dot{v} = -u\bar{Q}_2(u, v) = -u(2 + 7u - 2v + 5u^2 - 5uv - 2(3F + 2)v^2)$ .        (11)

34        We will study the system (11).

35        **Remark 3.** *Notice that the function  $P_2$  is symmetric under*

36        
$$\begin{aligned} (x, y, A, B) &\mapsto (x, -y, A, -B), \\ (x, y, A, B) &\mapsto (-x, y, -A, B), \end{aligned}$$

37        *analogously for  $Q_2$ .*

1 **Remark 4.** The cofactor of  $P_1(x, y) = 0$  is  $K_1(x, y) = -2Bx + 2Ay - 5ABx^2 +$   
 2  $(4B^2 - 4A^2)xy + 5ABY^2$  and the cofactor of  $Q_3(x, y) = 0$  is  $K_2(x, y) = -2K_1(x, y)$ .

3 **Proposition 3.** System (11), for  $F > 0$ , has the following singular points on  
 4 the coordinate axes:

- 5 (1) the origin which is a center;
- 6 (2)  $S_1 = (-1, 0)$  which is a saddle with eigenvalues  $\lambda_1 = (3F + \sqrt{9F^2 + 72F})/2$   
 7 and  $\lambda_2 = (3F - \sqrt{9F^2 + 72F})/2$ ;
- 8 (3)  $S_2 = (0, -1)$  which is a saddle with eigenvalues  $\lambda_1 = (-3F + \sqrt{9F^2 + 72F^3})/2$   
 9 and  $\lambda_2 = (-3F - \sqrt{9F^2 + 72F^3})/2$ ;
- 10 (4)  $S_3 = (-2/5, 0)$  with eigenvalues  $\lambda_1 = \frac{6}{5}\sqrt{F(9F - 4)}/5$  and  
 11  $\lambda_2 = \frac{-6}{5}\sqrt{F(9F - 4)}/5$ ;  $S_3$  is a saddle for  $F > 4/9$ , a center for  $0 < F < 4/9$   
 12 and a cusp for  $F = 4/9$ ;
- 13 (5)  $S_4 = (0, -2/5)$  with eigenvalues  $\lambda_1 = \frac{6}{5}\sqrt{(9 - 4F)}/5$  and  
 14  $\lambda_2 = \frac{-6}{5}\sqrt{(9 - 4F)}/5$ ;  $S_4$  is a saddle for  $0 < F < 9/4$ , a center for  $F > 9/4$   
 15 and a cusp for  $F = 9/4$ .

16 **Proposition 4.**

17 (i) If  $F = 1$  and  $A = B$ , then  $P_2(x, y) = Q_2(y, x)$  and the singular points of (11),  
 18 which are not on the coordinate axes, are:

- 19 (1)  $T_+^+ = ((5 + \sqrt{105})/20, (5 + \sqrt{105})/20)$  which is a saddle,  
 20 (2)  $T_-^+ = ((5 - \sqrt{105})/20, (5 - \sqrt{105})/20)$  which is a center.

21 (ii) If  $F = 1$  and  $A = -B$ , then  $P_2(x, y) = Q_2(-y, -x)$  and the singular points  
 22 of (11), which are not on the coordinate axes, are:

- 23 (1)  $T_+^- = ((5 + \sqrt{105})/20, -(5 + \sqrt{105})/20)$  which is a saddle,  
 24 (2)  $T_-^- = ((5 - \sqrt{105})/20, -(5 - \sqrt{105})/20)$  which is a center.

25 (iii) If  $F = 1$  then (11) has three pairs of singular points at infinity:

- 26 (1)  $(1 : -1 : 0)$  which is not elementary,  
 27 (2)  $(2 : 3 + \sqrt{5} : 0)$  which is a node,  
 28 (3)  $(2 : 3 - \sqrt{5} : 0)$  which is a node.

29 In the following theorem we prove that the system (10) has four real singular  
 30 points, besides  $S_1, S_2, S_3, S_4$  and the origin. They are not on the coordinate axes,  
 31 except for some special  $F \in \mathbb{R}$ .

32 **Theorem 1.**

33 (i) System (11) for  $F > 0, F \neq 1$ , has the following singular points:

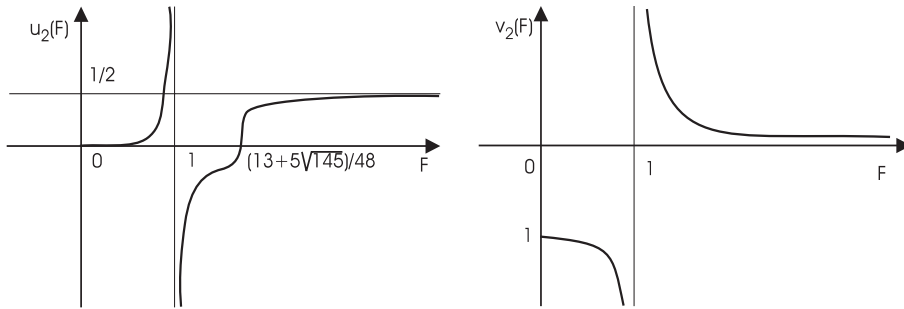
- 34 (1)  $T_1(F) = (u_1(F), v_1(F)) = (-F/(F - 1), 1/(F - 1))$  which is a saddle  
 35 with eigenvalues  $\lambda_1(F) = -6F/(F - 1)$  and  $\lambda_2(F) = 3F/(F - 1)$ ;

- 1 (2)  $T_2(F) = (u_2(F), v_2(F))$ , where  $u_2(F), v_2(F)$  are the real algebraic func-  
 2 tions;  $T_2(F)$  is a center if  $F \in (0, 1) \cup (1, (13 + 5\sqrt{145})/48)$ , and a saddle  
 3 if  $F \in ((13 + 5\sqrt{145})/48, +\infty)$ ;
- 4 (3)  $T_3(F) = (u_3(F), v_3(F))$ , where  $u_3(F), v_3(F)$  are the real algebraic func-  
 5 tions;  $T_3(F)$  is a saddle if  $F \in (0, 1) \cup (1, (13 + 5\sqrt{145})/48)$ , and a  
 6 center if  $F \in ((13 + 5\sqrt{145})/48, +\infty)$ ; if  $F = (13 + 5\sqrt{145})/48$  then  
 7  $T_2((13 + 5\sqrt{145})/48) = T_3((13 + 5\sqrt{145})/48)$ , and this singular point is  
 8 a center;
- 9 (4)  $T_4(F) = (u_4(F), v_4(F))$ , where  $u_4(F), v_4(F)$  are the real algebraic func-  
 10 tions;  $T_4(F)$  is a saddle if  $F \in (0, 4/9) \cup (9/4, +\infty)$ , and a center if  
 11  $F \in (4/9, 1) \cup (1, 9/4)$ ; if  $F = 4/9$  then  $T_4(4/9) = (-2/5, 0) = S_3$ , and  
 12 this is a cusp; if  $F = 9/4$  then  $T_4(9/4) = (0, -2/5) = S_4$ , and this is a  
 13 cusp.

14 (ii) System (11) for  $F > 0, F \neq 1$ , has four pairs of singular points at infinity  
 15 and they are all nodes.

16 **Proof.**

- 17 (i) (1) We prove it by straightforward calculation.  
 18 (2) The functions  $u_2, v_2$  are the irrational functions with explicit, but very  
 19 long expressions found by Maple; the only discontinuity is  $F = 1$ . The  
 20 graphs of the functions  $u_2, v_2$  are at Figure 2.



21 Figure 2.

22 The straightforward calculation shows that eigenvalues  $\lambda_1, \lambda_2$  are pure  
 23 imaginary for  $F < (13 + 5\sqrt{145})/48$ ; and for  $F > (13 + 5\sqrt{145})/48$  the  
 24 eigenvalues are real and  $\lambda_1 \lambda_2 < 0$ .

- 25 (3) The function  $v_3$  is found by Maple and it has a form

$$\begin{aligned}
 26 \quad v_3(F) &= -\frac{1}{6} \frac{K(F)^{1/3}}{L(F)} - \frac{1}{6} M(F) + \frac{10}{3} \frac{F(4F+1)}{L(F)} \\
 27 & - i \frac{\sqrt{3}}{2} \left( \frac{1}{3} \frac{K(F)^{1/3}}{L(F)} - \frac{1}{3} M(F) \right) \\
 28 & \qquad \qquad \qquad (12)
 \end{aligned}$$

1

where

$$\begin{aligned}
J(F) &= -F(497664F^8 - 412992F^7 - 2227248F^6 + 1399011F^5 \\
&\quad + 3698405F^4 - 1805109F^3 - 2815128F^2 + 1092528F + 1119744) \\
K(F) &= -41472F^7 - 249776F^6 - 30507F^5 + 539445F^4 + 148330F^3 \\
&\quad - 337788F^2 - 13824F + 110592 + J(F)^{1/2}(288F^3 + 261F^2 - 261F - 288) \\
L(F) &= (F - 1)(32F^2 + 61F + 61) \\
M(F) &= \frac{3456F^5 + 1180F^4 - 7855F^3 - 2225F^2 + 5640F + 2304}{L(F)K(F)^{1/3}}.
\end{aligned}$$

2

3

We want to prove that  $v_3(F)$  is a real function at  $\mathbb{R}^+$ . Since  $J(F) < 0$ ,

4

for each  $F > 0$ , then  $\sqrt{J(F)}$  is a pure imaginary number for each  $F > 0$ .

5

We denote  $\sqrt{J(F)} = d(F)i$ , where  $d(F)$  is a real function, then

6

$$K(F) = P_7(F) + d(F)i(F - 1)(288F^2 + 549F + 288)$$

7

where

$$\begin{aligned}
P_7(F) &= -41472F^7 - 249776F^6 - 30507F^5 + 539445F^4 + 148330F^3 \\
&\quad - 337788F^2 - 13824F + 110592.
\end{aligned}$$

8

9

Let

10

$$P_5(F) = 3456F^5 + 1180F^4 - 7855F^3 - 2225F^2 + 5640F + 2304$$

11

then

12

$$M(F) = \frac{P_5(F)}{L(F)K(F)^{1/3}};$$

13

let

14

$$\begin{aligned}
f_1(F) &= \frac{10}{3} \frac{F(4F+1)}{L(F)} \\
f_2(F) &= -\frac{1}{6L(F)}(K(F)^{1/3} + \frac{P_5(F)}{K(F)^{1/3}}) - i\sqrt{3}(K(F)^{1/3} - \frac{P_5(F)}{K(F)^{1/3}})
\end{aligned}$$

15

then  $v_3(F) = f_1(F) + f_2(F)$ . Notice that  $f_1(F) \in \mathbb{R}$  for each  $F > 0$ ,

16

and we need to show that  $Im(f_2(F)) = 0$  for each  $F > 0$ . That is true

17

if  $|K(F)^{1/3}|^2 = P_5(F)$ , but this is a straightforward calculation.

18

The function

19

$$u_3(F) = -\frac{8v_3(F)^2F^2 + 9v_3(F)^2F + 8v_3(F)^2 - 9v_3(F)F + 4v_3(F) - 6F - 4}{15v_3(F)F + 10v_3(F) - 6F - 14}$$

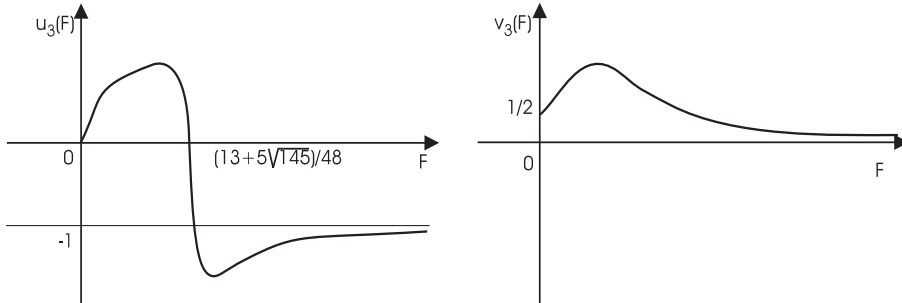
20

is also real, because  $v_3(F)$  is real. The graphs of the functions  $u_3, v_3$  are

21

at *Figure 3*.

1



2

Figure 3.

3

The topological type is checked analogously as in the part (2) of this proof.

4

5

To study the singularities  $T_2$  and  $T_3$  for  $F = (13 + 5\sqrt{145})/48$  we consider limit  $F \rightarrow (13 + 5\sqrt{145})/48^+$  and  $F \rightarrow (13 + 5\sqrt{145})/48^-$ , and compute that  $T_2((13 + 5\sqrt{145})/48) = T_3((13 + 5\sqrt{145})/48)$ . We compute the normal form for the nilpotent case and prove that we have a center.

6

7

8

9

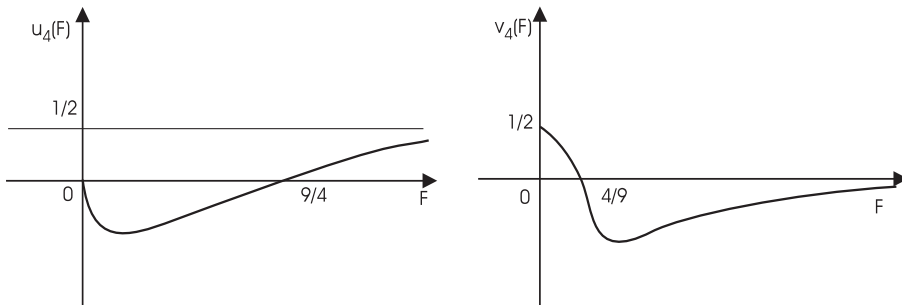
- (4) Proof that the functions  $u_4, v_4$  are real is analogous as in the part (3), because  $v_4$  is the conjugate complex function of the function  $v_3$  in the form (12)

10

11

12

The graphs of the functions  $u_4, v_4$  are at Figure 4.



13

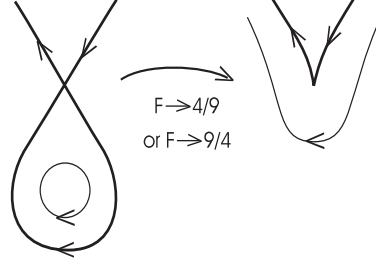
Figure 4.

14

For  $F = 4/9$  and  $F = 9/4$  we have nilpotent case and a coincidence of singularities  $T_4$  and  $S_3$ , i.e.  $T_4$  and  $S_4$ , see Proposition 3.

15

1



2

Figure 5.

3

(ii) Analogously as in *Proposition 2* we make the change of coordinates and find four pairs of functions; then we prove, in the same way as in (i), that these functions are real for  $F > 0$ ,  $F \neq 1$ .

4

5

6

□

7

This proposition shows “moving” of the points  $T_1, T_2, T_3, T_4$  on the Poincaré disc, if the parameter goes to infinity, or it goes to zero, or the coordinate functions have discontinuity.

8

9

10

**Proposition 5.** For  $T_1(F), T_2(F), T_3(F), T_4(F)$  defined in *em Theorem 1*, the following statements are valid:

11

12

(1)

$$\begin{aligned} \lim_{F \rightarrow \infty} T_1(F) &= \lim_{F \rightarrow \infty} T_3(F) = (-1, 0) = S_{3A}(1), \\ \lim_{F \rightarrow \infty} T_2(F) &= \lim_{F \rightarrow \infty} T_4(F) = (1/2, 0) = S_{3A}(-16/11); \end{aligned}$$

13

14

(2)

$$\begin{aligned} T_1(0) &= T_2(0) = (0, -1) = S_{3B}(1), \\ T_3(0) &= T_4(0) = (0, 1/2) = S_{3B}(-16/11), \end{aligned}$$

15

16

where the point  $S_{3B}$  is defined analogous as the point  $S_{3A}$  in *Proposition 1*;

17

(3)

$$\begin{aligned} T_3(1) &= ((5 + \sqrt{105})/20, (5 + \sqrt{105})/20) = T_+^+, \\ T_4(1) &= ((5 - \sqrt{105})/20, (5 - \sqrt{105})/20) = T_-^+, \end{aligned}$$

18

19

(4)

$$\begin{aligned} \lim_{F \rightarrow 1^+} T_1(F) &= \lim_{F \rightarrow 1^+} T_2(F) = (-\infty, +\infty), \\ \lim_{F \rightarrow 1^-} T_1(F) &= \lim_{F \rightarrow 1^-} T_2(F) = (-\infty, +\infty). \end{aligned}$$

20

21

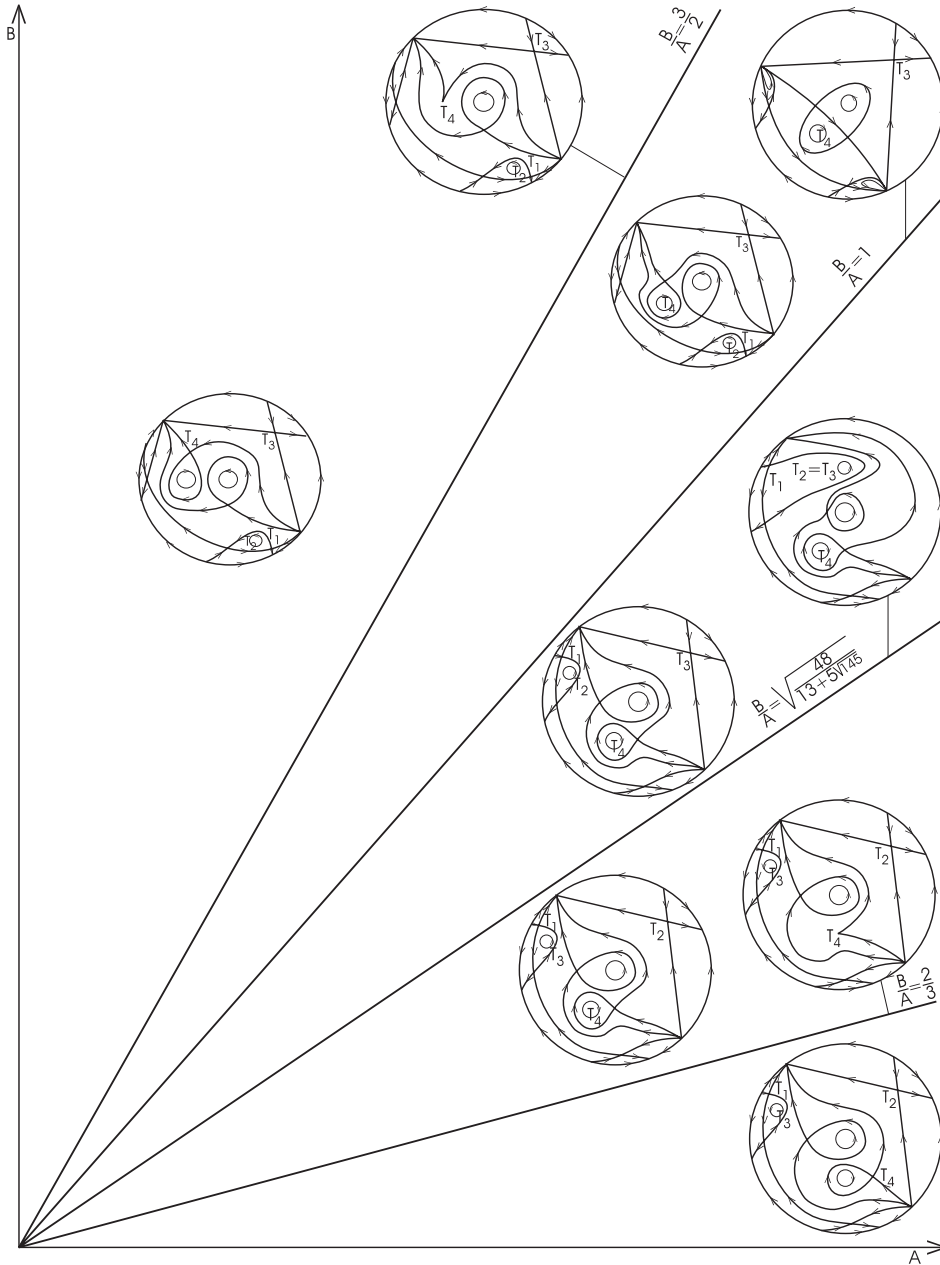
The bifurcation diagram of the phase portraits of the system (10), drawn by using all facts from *Propositions* and *Theorem 1*, appears at *Figure 6*. Due to the symmetry of the system (11), it is only necessary to draw the bifurcation diagram for systems (10) for  $A > 0$ ,  $B > 0$ .

22

23

24

1



2

Figure 6.

3

4

5

**Remark 5.** The bifurcation diagram of the Hamiltonian vector field  $X_{H_1}$ , with Hamiltonian  $H_1 = P_1Q_3$ , satisfying condition b) from 1. Introduction, has less bifurcation curves than the bifurcation diagram of  $V_H$ , drawn at Figure 6. The

bifurcation curves of  $X_{H_1}$  are:  $\frac{B}{A} = \frac{1}{\sqrt{3}}$ ,  $\frac{B}{A} = 1$  and  $\frac{B}{A} = \sqrt{3}$ . In the bifurcation diagram of  $X_{H_1}$  the “replacement” of  $T_2$  and  $T_3$  is done at bifurcation line  $\frac{B}{A} = 1$ , and also at  $\frac{B}{A} = 1$  we have a coincidence of  $T_3$  and  $T_4$ .

We find interesting the study of the perturbed systems of (8) and (10). The next step will be the study of the existence of limit cycles of the system

$$\dot{x} = f(x) + \varepsilon g(x),$$

which is nonintegrable.

## 7. Invariant curves of the systems (10)

The zero level invariant curves of (10) are two algebraic curves, a straight line  $P_1(x, y) = Ax + By + 1 = 0$ , and a cubic curve  $Q_3(x, y) = Ax^3 - 2Bx^2y - 2Axy^2 + By^3 + x^2 + y^2 = 0$ , which are factors of  $H(x, y) = (Ax + By + 1)^2(Ax^3 - 2Bx^2y - 2Axy^2 + By^3 + x^2 + y^2) = 0$ .

If  $A = B = 0$  then the straight line becomes the line at infinity, and the cubic curve becomes the reducible conic  $x^2 + y^2 = 0$ .

The discriminant of the cubic equation  $Ax^3 + (-2By + 1)x^2 - 2Ay^2x + By^3 + y^2 = 0$  is a function of  $y$ . We find the number of the connected components of  $Q_3 = 0$  using the discriminant, in the same way as in [RS]. The cubic curve has 3 connected components for each  $A, B \geq 0$ .

**Example 2.** In this example we describe the invariant curves of the system (6.1.) for  $A = B$ . The singularity  $(-1, 0)$  lies on the curves  $P_1 = 0$  and  $Q_3 = 0$ , these curves passes through this point. The origin lies on the curve  $Q_3 = 0$ , but the curve does not pass through. The saddles  $(-2/5, 0)$  and  $(0, -2/5)$  lie on the curve  $H = P_1^2 Q_3 = C$ ,  $C \neq 0$  and we have a saddle connection. The singularity  $((5 + \sqrt{105})/20, (5 + \sqrt{105})/20)$  lies on the curve  $H = P_1^2 Q_3 = C$ , for some other  $C \neq 0$ , this point is a self-intersecting point of the curve. The singularity  $((5 - \sqrt{105})/20, (5 - \sqrt{105})/20)$  lies on the curve  $H = C$ ,  $C \neq 0$  but the curve does not pass through.

The phase portraits at Figure 6 are determined by the bifurcations of the curve  $H = C$ ,  $C \neq 0$ .

## References

- [BM] M. BRUNELLA, M. MIARI, *Topological equivalence of a planar vector field with its principal part defined through Newton polyhedra*, Journal of Differential Equations **85**(1990), 338-366.
- [D] F. DUMORTIER, *Singularities of vector fields on the plane*, Journal of Differential Equations **23**(1977), 53-106.
- [LS] V. A. LUNKEVICH, K. S. SIBIRSKY, *Conditions of a center in homogeneous nonlinearities of third degree*, Differential Equations **1**(1965), 1164-1168.

- 1 [M] K. E. MALKIN, *Criteria for center of a differential equation*, Volg. Matem.  
2 Sbornik **2**(1964), 87-91.
- 3 [MM-JR] P. MARDEŠIĆ, L. MOSER-JAUSLIN, C. ROUSSEAU, *Darboux linearization and*  
4 *isochronous centers with a rational first integral*, Journal of Differential Equa-  
5 tions **134**(1997), 216-268.
- 6 [MRT] P. MARDEŠIĆ, C. ROUSSEAU, B. TONI, *Linearization of isochronous centers*,  
7 Journal of Differential Equations **121**(1995), 67-108.
- 8 [PS] J. PAL, D. SCHLOMIUK, *Summing up the dynamics of quadratic Hamiltonian*  
9 *systems with a center*, Canadian Journal of Mathematics **49**(1997), 583-599.
- 10 [P1] H. POINCARÉ, *Mémoire sur les courbes définies par les équations différentielles*,  
11 J. de Math. **37**(1881), 375-422; **8**(1882), 251-296; Oeuvres Henri Poincaré,  
12 vol. I, Gauthiers-Villars, Paris (1951), 3-84
- 13 [P2] H. POINCARÉ, *Mémoire sur les courbes définies par les équations différentielles*,  
14 J. Math. Pures Appl. **4**(1885), 167-244; Oeuvres Henri Poincaré, vol. I,  
15 Gauthiers-Villars, Paris (1951), 95-114
- 16 [RS] C. ROUSSEAU, D. SCHLOMIUK, *Cubic vector fields symmetric with respect to*  
17 *a center*, Journal of Differential Equations **123**(1995), 388-436.
- 18 [RST] C. ROUSSEAU, D. SCHLOMIUK, P. THIBAudeau, *The centers in the reduced*  
19 *Kukles systems*, Nonlinearity **8**(1995), 541-569.
- 20 [S] D. SCHLOMIUK, *Algebraic particular integrals, integrability and the problem*  
21 *of the center*, Transactions of the American Mathematical Society **338**(1993),  
22 799-841.
- 23 [So] J. SOKULSKI, *The beginning of classification of Darboux integrals for cubic*  
24 *systems with center*, preprint
- 25 [T] B. TONI, *Branching of periodic orbits from Kukles isochrones*, Electronic Jour-  
26 nal of Differential Equations, **1998**(13)(1998), 1-10.
- 27 [Ž] V. ŽUPANOVIĆ, *Topological equivalence of planar vector fields and their gen-*  
28 *eralised principal part*, Journal of Differential Equations, **167**(2000), 1-15.
- 29 [Ž1 ] V. ŽUPANOVIĆ, *Integrable cubic vector fields with a center*, preprint